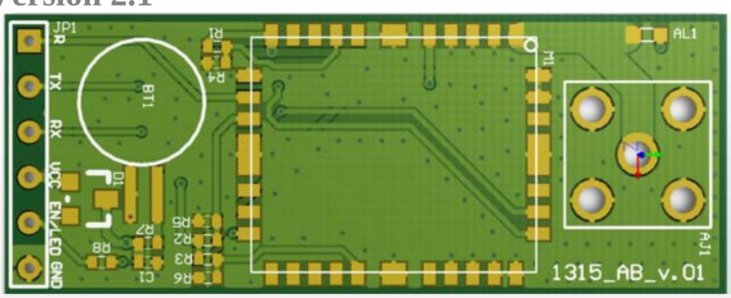
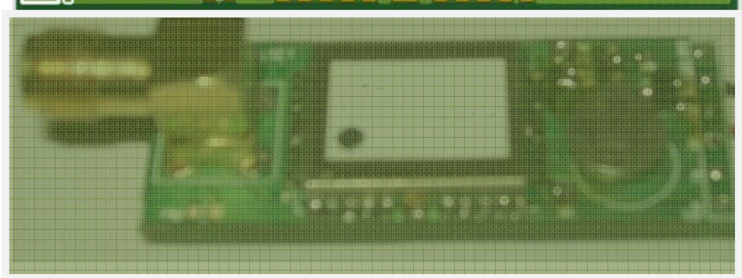
RASTA-SMA-1513-GEB V.10
GPS Engine Board

65 channels with ultra-high sensitive GPS engine board

Data Sheet

Version 2.1





Abstract

Technical data sheet describing the cost effective, high-performance **RASTA-SMA-1513-GEB V1.0** based series of ultra high sensitive GPS modules.

The **RASTA-SMA-1513-GEB V1.0**is a GPS module that is sensitive to ***electrostatic dis- charge* (ESD)**. Please handle with appropriate care.

GPS Modules

www.i2rlabs.com

RASTA-SMA-1513-GEB V1.0

Super-fast Acquisition and Ultra-high Sensitivity 65 Channels GPS engine board

FEATURES

- 65 Channel GPS L1 C/A Code
- Perform 8 million time-frequency hypothesis testing per second
- Open sky hot start 1 sec, cold start 29 sec
- Signal detection better than -161dBm
- Multipath detection and suppression
- Accuracy 2.5m CEP
- Maximum update rate 10Hz
- Tracking current ~23mA
- Provides a 6pin header to easily connect to PCB
- 5m CEP Accuracy
- RoHS compliance

The RASTA-SMA-1513-GEB V1.0module is small, single-board, 65 parallel-channels receiver intended for Original Equipment Manufacturer (OEM) products.

The receiver continuously tracks all satellites in view and provides accurate satellite positioning data. The RASTA-SMA-1513-GEB V1.0is optimized for applications requiring good performance, low cost, and maximum flexibility; suitable for a wide range of OEM configurations including handhelds, asset tracking, marine and vehicle navigation products.

Its 65 parallel channels provide fast satellite signal acquisition and short startup time. Acquisition sensitivity of –145dm and tracking sensitivity of –161dBm offers good navigation performance even in urban canyons having limited sky view.

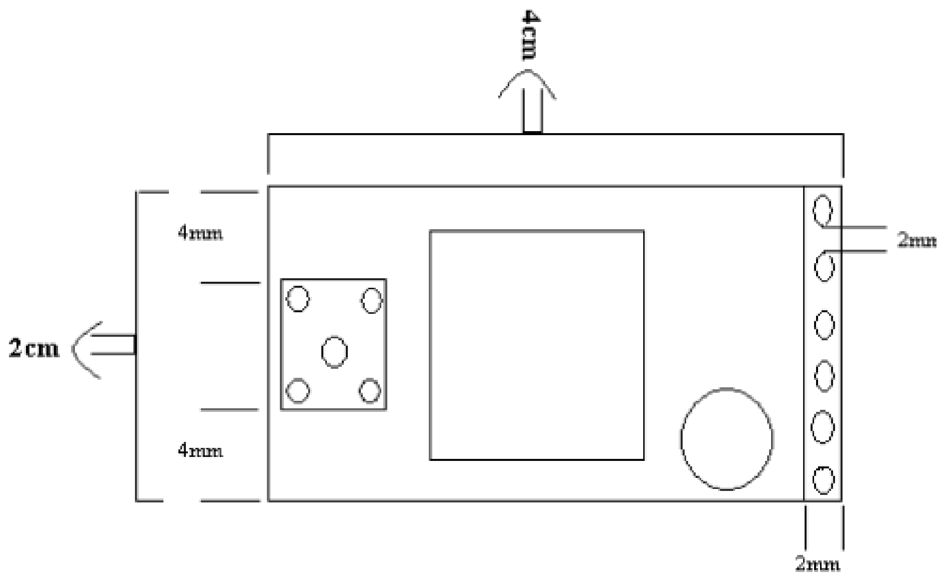
Satellite-based augmentation systems, such as WAAS and EGNOS, are supported to yield improved accuracy.

Users can modify the NMEA sentences and Binary code

TECHNICAL SPEICIFICAIONS

Parameter	Specification
Receiver Type	65 Channels GPS L1 frequency, C/A Code
Time-To-First-Fix	Cold Start (Autonomous) 29s (Average, under open sky) Warm Start (Autonomous) 5s (Average, under open sky) Hot Start (Autonomous) 1s (Average, under open sky)
Sensitivity	Tracking & Navigation -161 dBm Reacquisition -161 dBm Cold Start (Autonomous) -145 dBm
Accuracy	Autonomous 2.5 m CEP Velocity 0.1 m/sec (without aid) Time 300 ns RMS 30 ns 99% <60 ns Compensated[5] 15 ns
Max Update Rate	Supports 1 / 2 / 4 / 5 / 8 / 10 Hz update rate (1Hz default)
Velocity Accuracy	0.1m/s
Heading Accuracy	0.5 degrees
Dynamics	□ 4 G (39.2 m/sec)
Operational Limits	Velocity 515 m/s (1000 knots) Altitude <18000 meters (COCOM limit, either may be exceeded but not both)
RF connector	SMA
Serial Interface	3.3V LVTTL level, 10 pin 2mm male header
Datum	Default WGS-84 User definable
Input Voltage	3.3V -3.6 V DC +/-10%
Input Current	~36 mA tracking
Dimension	4L x 1.5W x 0.4H (cm)
Weight	5g

MECHANICAL CHARACTERISTICS



PINOUT DESCRIPTION

Pin Number	Signal Name	Description
1	GND	Ground
2	LED	
3	VCC	Regulated 3.3V – 3.6 Volt power input
4	Rx	Asynchronous serial input at LVTTL level, to input commands
5	Tx	Asynchronous serial output at LVTTL level, to output NMEA message
6	RESET IN	Reset input, active LOW

NMEA Messages

The serial interface protocol is based on the National Marine Electronics Association's NMEA 0183 ASCII interface specification. This standard is fully define in "NMEA 0183, Version 3.01" The standard may be obtained from NMEA, www.nmea.org.com

GGA - GPS FIX DATA

Time, position and position-fix related data (number of satellites in use, HDOP, etc.).

Format:
$GPGGA,<1>,<2>,<3>,<4>,<5>,<6>,<7>,<8>,<9>,M,<10>,M,<11>,<12>,*<13><CR><LF>

Example:
$GPGGA,104549.04,2447.2038,N,12100.4990,E,1,06,01.7,00078.8,M,0016.3,M,,*5C<CR><LF>

Field	Example	Description
1	104549.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
2	2447.2038	Latitude in ddmm.mmmm format Leading zeros transmitted
3	N	Latitude hemisphere indicator, 'N' = North, 'S' = South
4	12100.4990	Longitude in dddmm.mmmm format Leading zeros transmitted
5	E	Longitude hemisphere indicator, 'E' = East, 'W' = West
6	1	Position fix quality indicator 0: position fix unavailable 1: valid position fix, SPS mode 2: valid position fix, differential GPS mode
7	06	Number of satellites in use, 00 ~ 12
8	01.7	Horizontal dilution of precision, 00.0 ~ 99.9
9	00078.8	Antenna height above/below mean sea level, -9999.9 ~ 17999.9
10	0016.3	Geoidal height, -999.9 ~ 9999.9
11		Age of DGPS data since last valid RTCM transmission in xxx format (seconds) NULL when DGPS not used
12		Differential reference station ID, 0000 ~ 1023 NULL when DGPS not used
13	5C	Checksum

Note: The checksum field starts with a '*' and consists of 2 characters representing a hex number. The
checksum is the exclusive OR of all characters between '$' and '*'.

GLL - LATITUDE AND LONGITUDE, WITH TIME OF POSITION FIX AND STATUS

Latitude and longitude of current position, time, and status.

Format:
$GPGLL,<1>,<2>,<3>,<4>,<5>,<6>,<7>*<8><CR><LF>

Example:
$GPGLL,2447.2073,N,12100.5022,E,104548.04,A,A*65<CR><LF>

Field	Example	Description
1	2447.2073	Latitude in ddmm.mmmm format Leading zeros transmitted
2	N	Latitude hemisphere indicator, ‘N’ = North, ‘S’ = South
3	12100.5022	Longitude in dddmm.mmmm format Leading zeros transmitted
4	E	Longitude hemisphere indicator, 'E' = East, 'W' = West
5	104548.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
6	A	Status, ‘A’ = valid position, ‘V’ = navigation receiver warning
7	A	Mode indicator ‘N’ = Data invalid ‘A’ = Autonomous ‘D’ = Differential ‘E’ = Estimated
8	65	Checksum

GSA-GPS DOP AND ACTIVE SATELLITES

GPS receiver operating mode, satellites used for navigation, and DOP values.

Format:
$GPGSA,<1>,<2>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<3>,<4>,<5>,<6>*<7><CR><LF>
Example:

$GPGSA,A,3,26,21,,,09,17,,,,,,,10.8,02.1,10.6*07<CR><LF>

Field	Example	Description
1	A	Mode, ‘M’ = Manual, ‘A’ = Automatic
2	3	Fix type, 1 = not available, 2 = 2D fix, 3 = 3D fix
3	26,21,,,09,17,,,,,,	PRN number, 01 to 32, of satellite used in solution, up to 12 transmitted
4	10.8	Position dilution of precision, 00.0 to 99.9
5	02.1	Horizontal dilution of precision, 00.0 to 99.9
6	10.6	Vertical dilution of precision, 00.0 to 99.9
7	07	Checksum

GSV - GPS SATELLITE IN VIEW

Number of satellites in view, PRN number, elevation angle, azimuth angle, and C/No. Only up to four satellite details are transmitted per message. Additional satellite in view information is sent in subsequent GSV messages.

Format:
$GPGSV,<1>,<2>,<3>,<4>,<5>,<6>,<7>,…,<4>,<5>,<6>,<7> *<8><CR><LF>

Example:
$GPGSV,2,1,08,26,50,016,40,09,50,173,39,21,43,316,38,17,41,144,42*7C<CR><LF>
$GPGSV,2,2,08,29,38,029,37,10,27,082,32,18,22,309,24,24,09,145,*7B<CR><LF>

Field	Example	Description
1	2	Total number of GSV messages to be transmitted
2	1	Number of current GSV message
3	08	Total number of satellites in view, 00 ~ 12
4	26	Satellite PRN number, GPS: 01 ~ 32, SBAS: 33 ~ 64 (33 = PRN120)
5	50	Satellite elevation number, 00 ~ 90 degrees
6	016	Satellite azimuth angle, 000 ~ 359 degrees
7	40	C/No, 00 ~ 99 dB Null when not tracking
8	7C	Checksum

RMC - RECOMMANDED MINIMUM SPECIFIC GPS/TRANSIT DATA

Time, date, position, course and speed data.

Format:
$GPRMC,<1>,<2>,<3>,<4>,<5>,<6>,<7>,<8>,<9>,<10>,<11>,<12>*<13><CR><LF>

Example:
$GPRMC,104549.04,A,2447.2038,N,12100.4990,E,016.0,221.0,250304,003.3,W,A*22<CR><LF>

Field	Example	Description
1	104549.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
2	A	Status, ‘V’ = navigation receiver warning, ‘A’ = valid position
3	2447.2038	Latitude in dddmm.mmmm format Leading zeros transmitted
4	N	Latitude hemisphere indicator, ‘N’ = North, ‘S’ = South
5	12100.4990	Longitude in dddmm.mmmm format Leading zeros transmitted
6	E	Longitude hemisphere indicator, 'E' = East, 'W' = West
7	016.0	Speed over ground, 000.0 ~ 999.9 knots
8	221.0	Course over ground, 000.0 ~ 359.9 degrees
9	250304	UTC date of position fix, ddmmyy format
10	003.3	Magnetic variation, 000.0 ~ 180.0 degrees
11	W	Magnetic variation direction, ‘E’ = East, ‘W’ = West
12	A	Mode indicator ‘N’ = Data invalid ‘A’ = Autonomous ‘D’ = Differential ‘E’ = Estimated
13	22	Checksum

VTG - COURSE OVER GROUND AND GROUND SPEED

Velocity is given as course over ground (COG) and speed over ground (SOG).

Format:

GPVTG,<1>,T,<2>,M,<3>,N,<4>,K,<5>*<6><CR><LF>

Example:

$GPVTG,221.0,T,224.3,M,016.0,N,0029.6,K,A*1F<CR><LF>

Field	Example	Description
1	221.0	True course over ground, 000.0 ~ 359.9 degrees
2	224.3	Magnetic course over ground, 000.0 ~ 359.9 degrees
3	016.0	Speed over ground, 000.0 ~ 999.9 knots
4	0029.6	Speed over ground, 0000.0 ~ 1800.0 kilometers per hour
5	A	Mode indicator 'N' = Data invalid 'A' = Autonomous 'D' = Differential 'E' = Estimated
6	1F	Checksum

ZDA TIME AND DATE

Format:

$GPZDA,<1>,<2>,<3>,<4>,<5>,<6>*<7><CR><LF>

Example:

$GPZDA,104548.04,25,03,2004,,*6C<CR><LF>

Field	Example	Description
1	104548.04	UTC time in hhmmss.ss format, 000000.00 ~ 235959.99
2	25	UTC time: day (01 ... 31)
3	03	UTC time: month (01 ... 12)
4	2004	UTC time: year (4 digit year)
5		Local zone hour Not being output by the receiver (NULL)
6		Local zone minutes Not being output by the receiver (NULL)
7	6C	Checksum

Binary Messages

See *Binary Message Protocol User's Guide* for detailed descriptions.

Contact Information

We hope this datasheet will be helpful to the user to get the most out of the GPS module, furthermore feedback inputs about errors or mistakable verbalizations and comments or proposals to **I2R LABS** for further improvements are highly appreciated.

I2R LABS
IDEAS INTO REALITY

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